

# *On Local Fixing*



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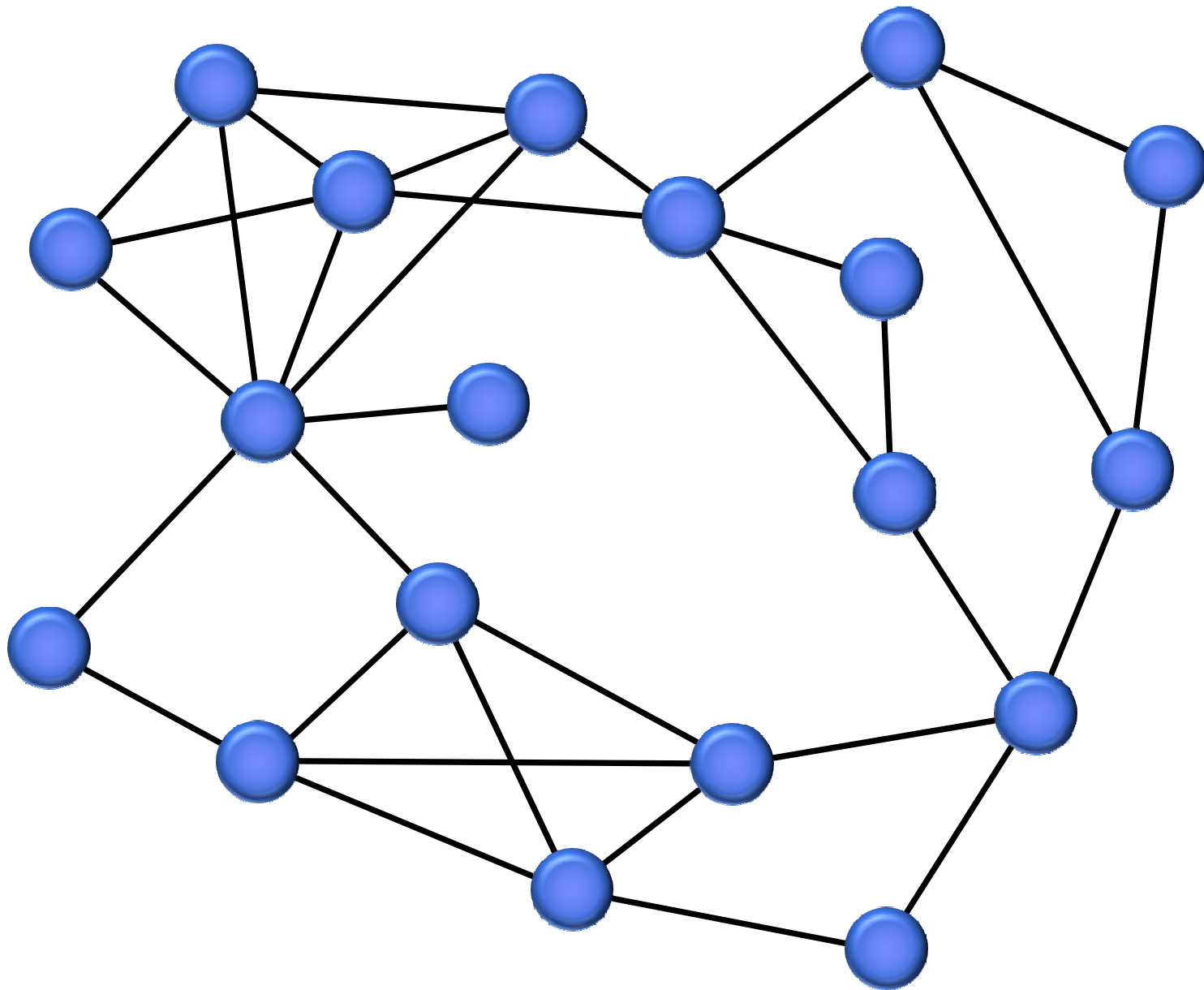
# Motivation



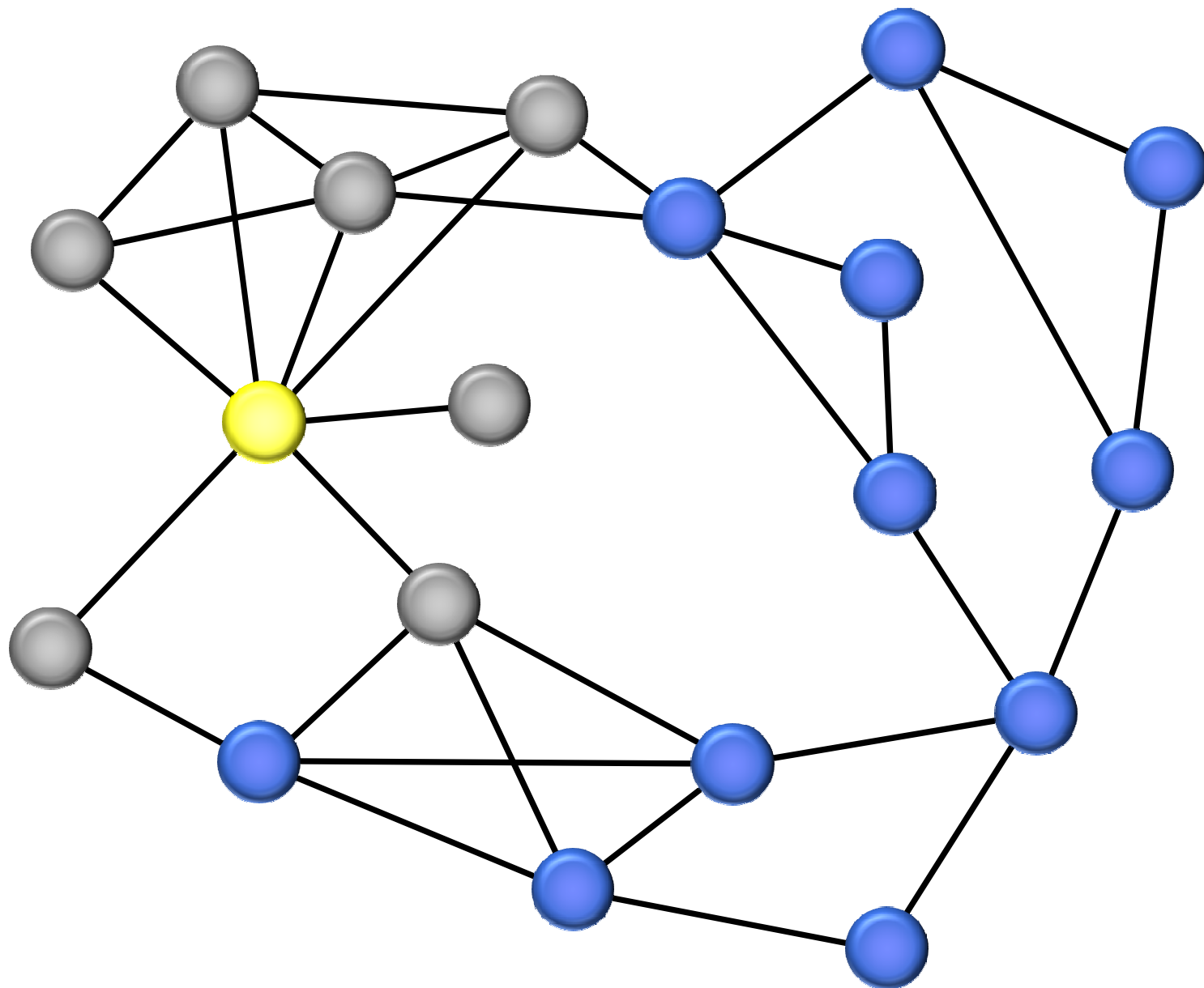
# Motivation



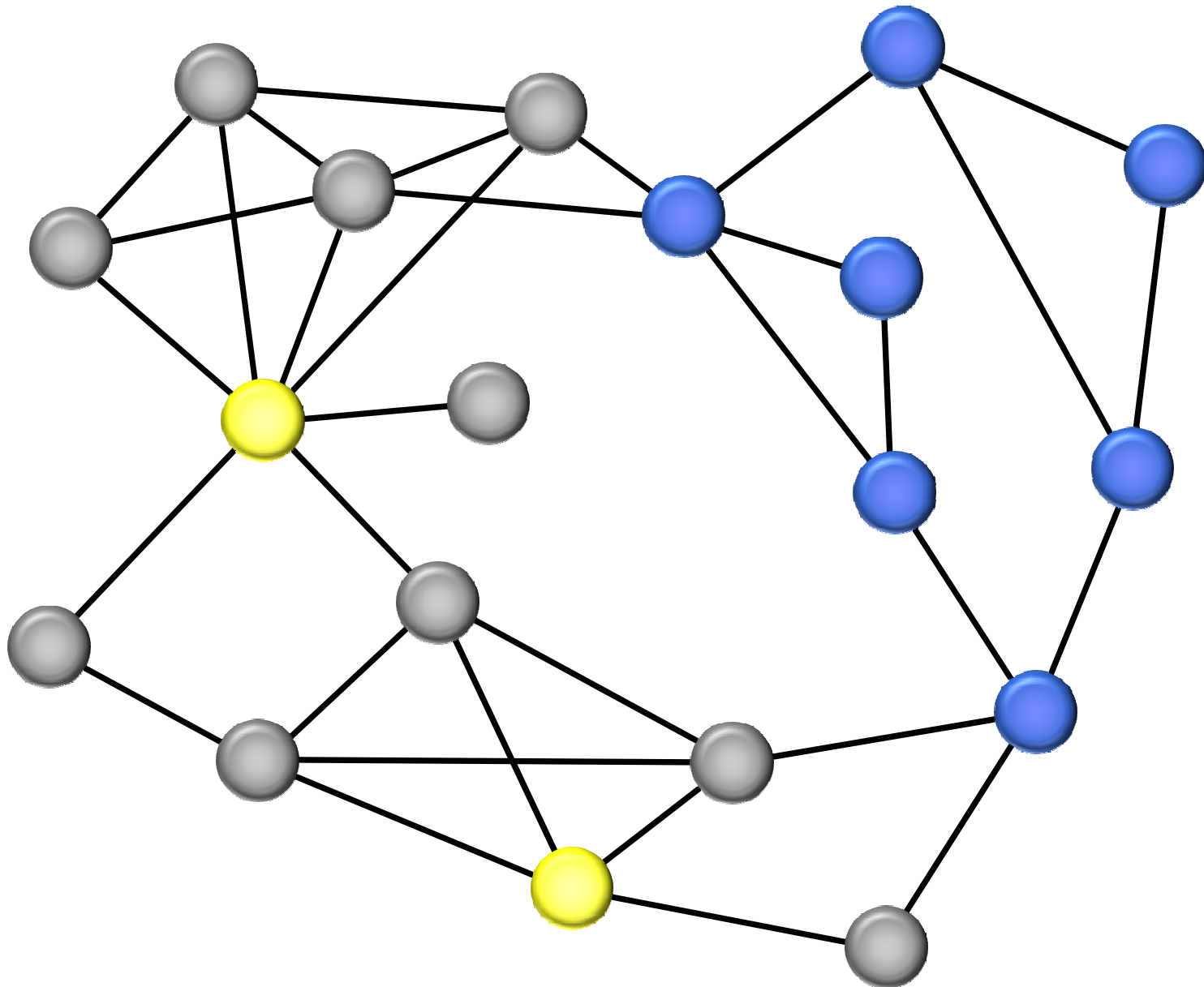
# Motivation by Example



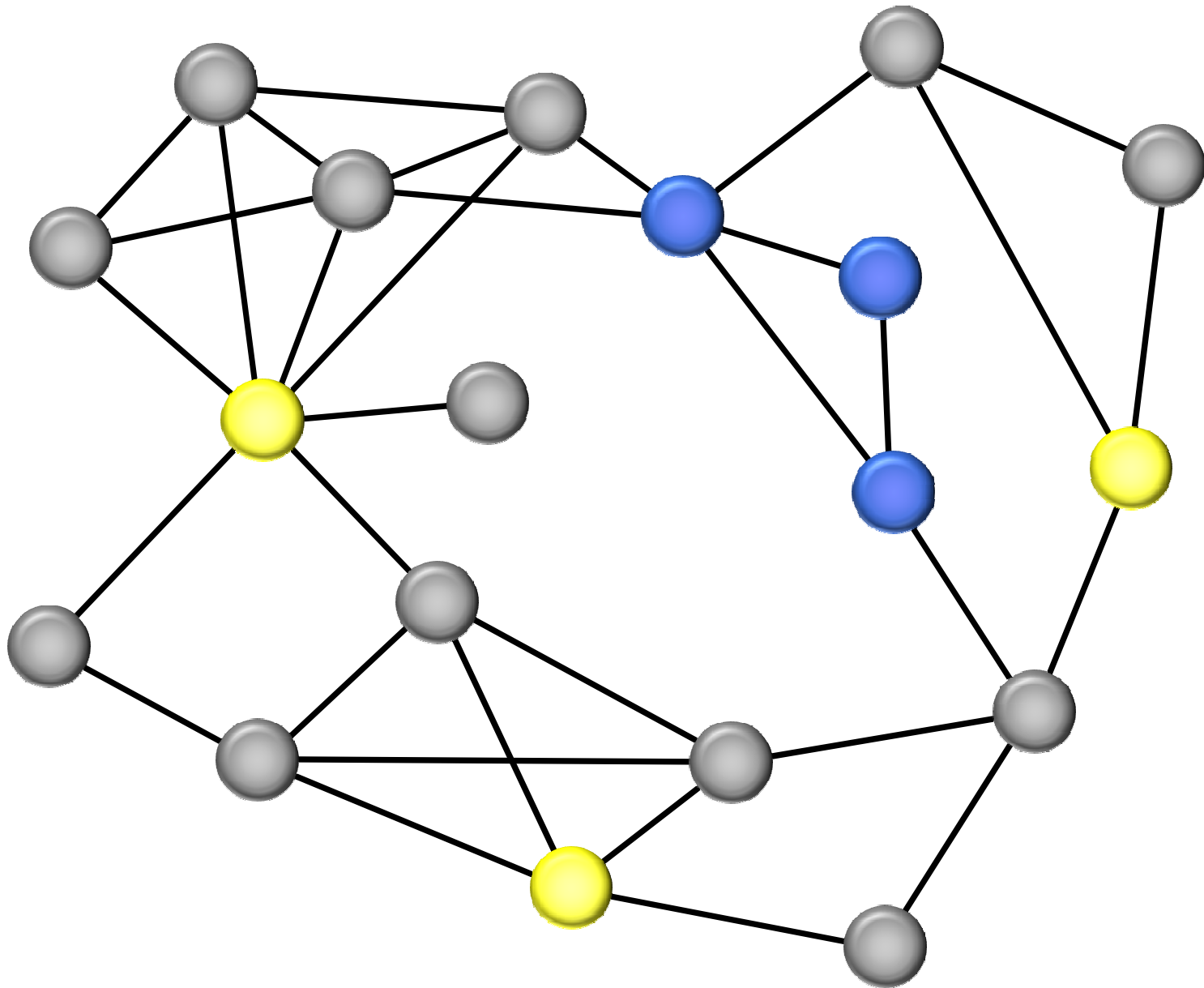
# Motivation by Example



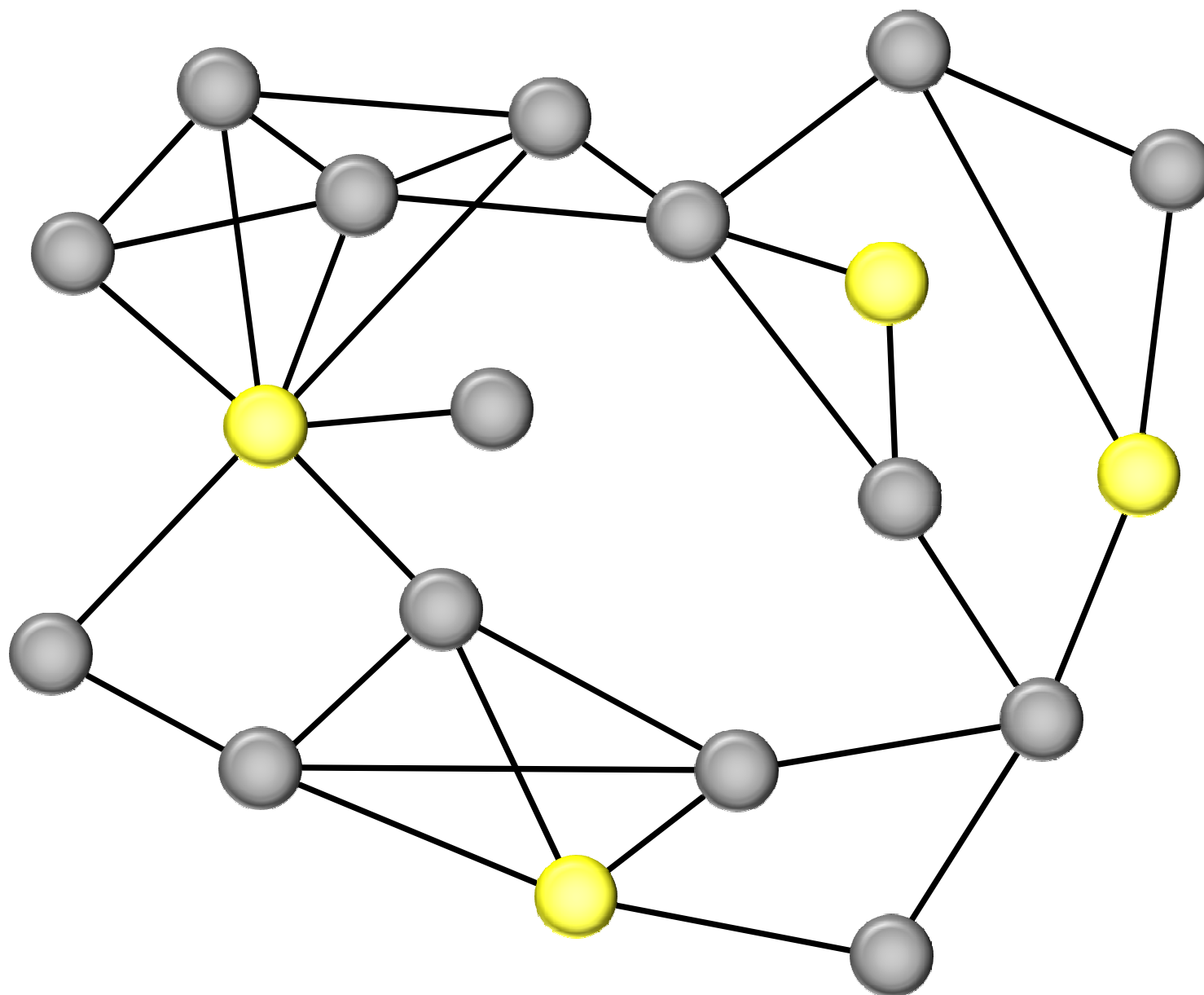
# Motivation by Example



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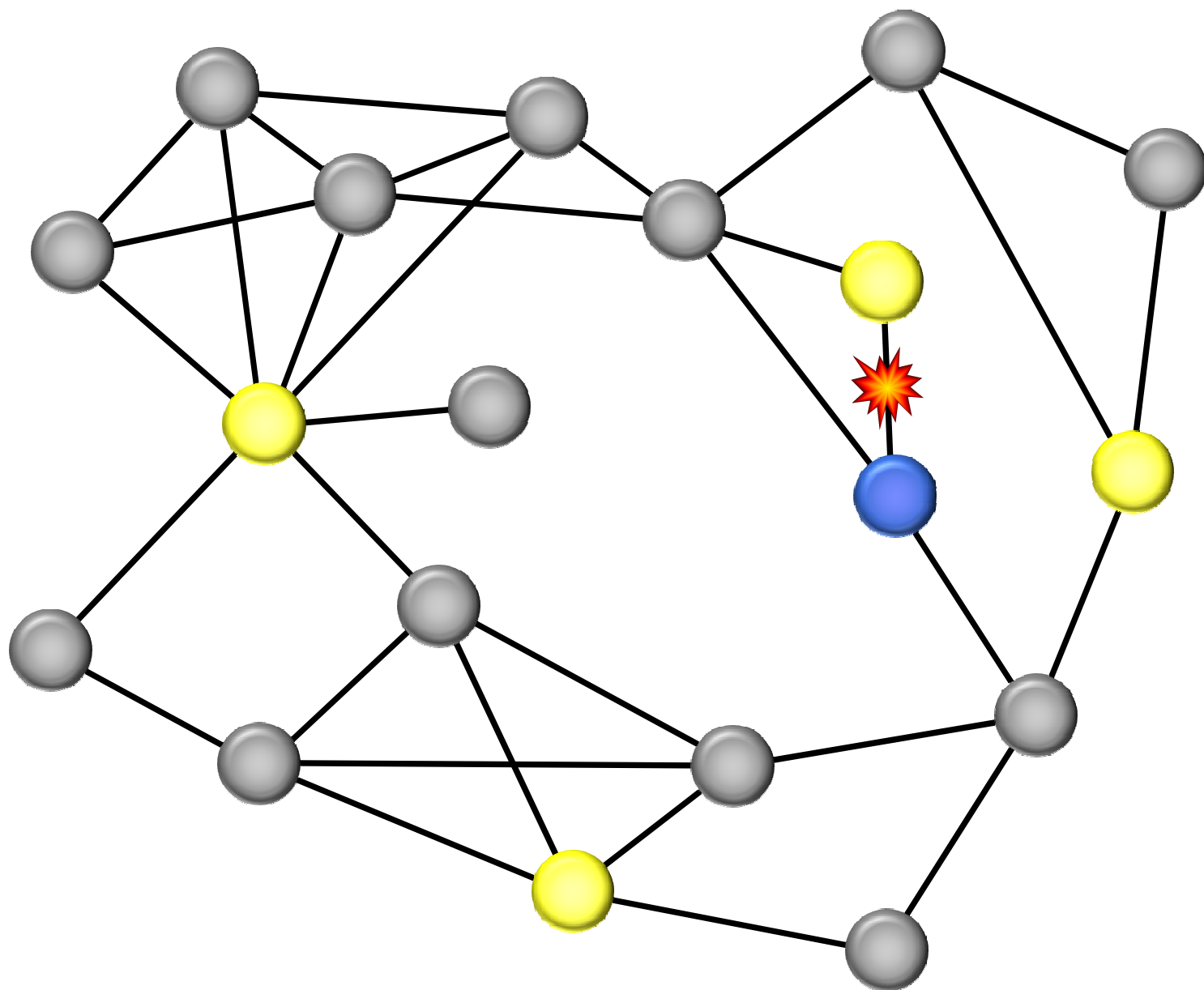


# Motivation by Example

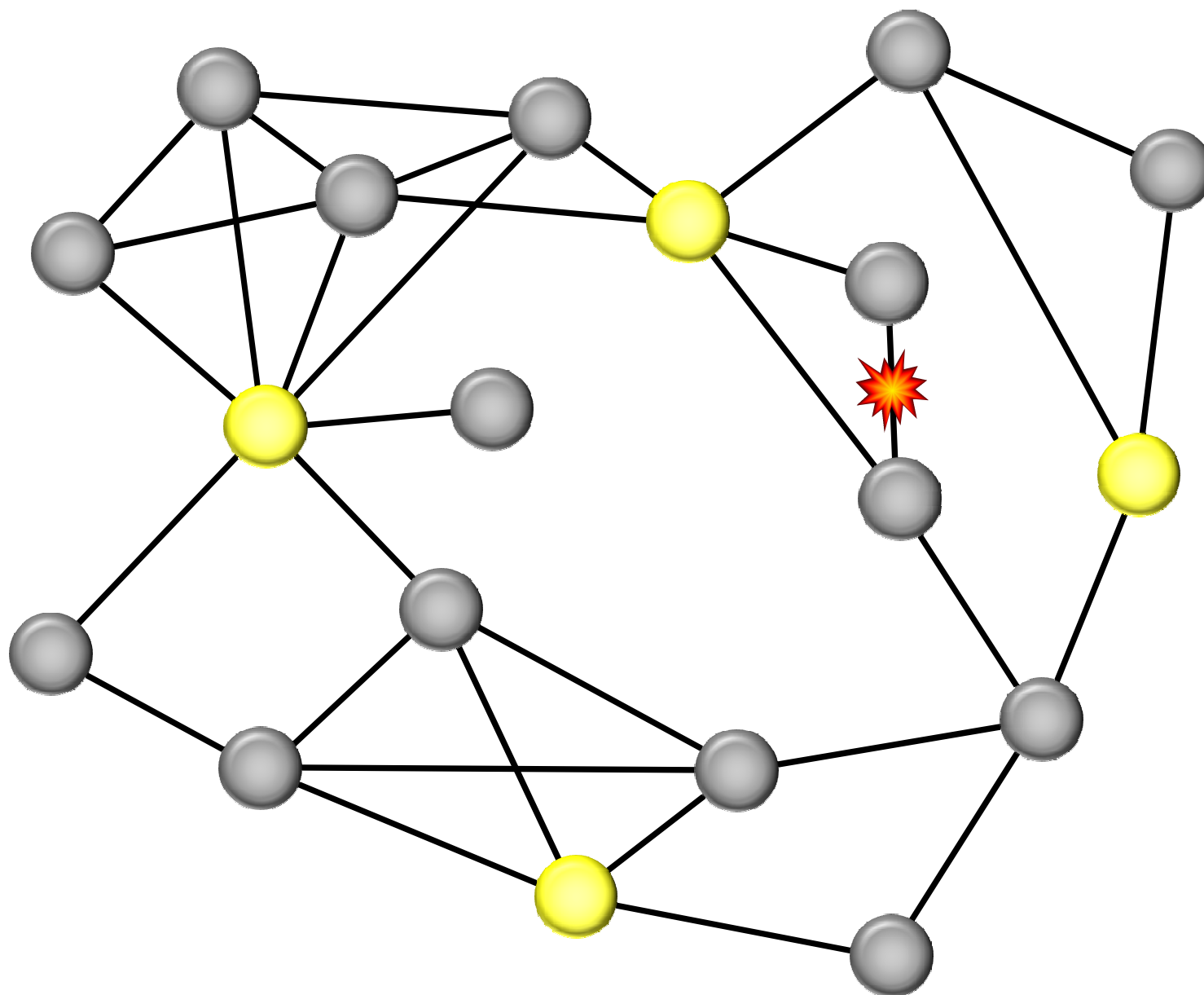




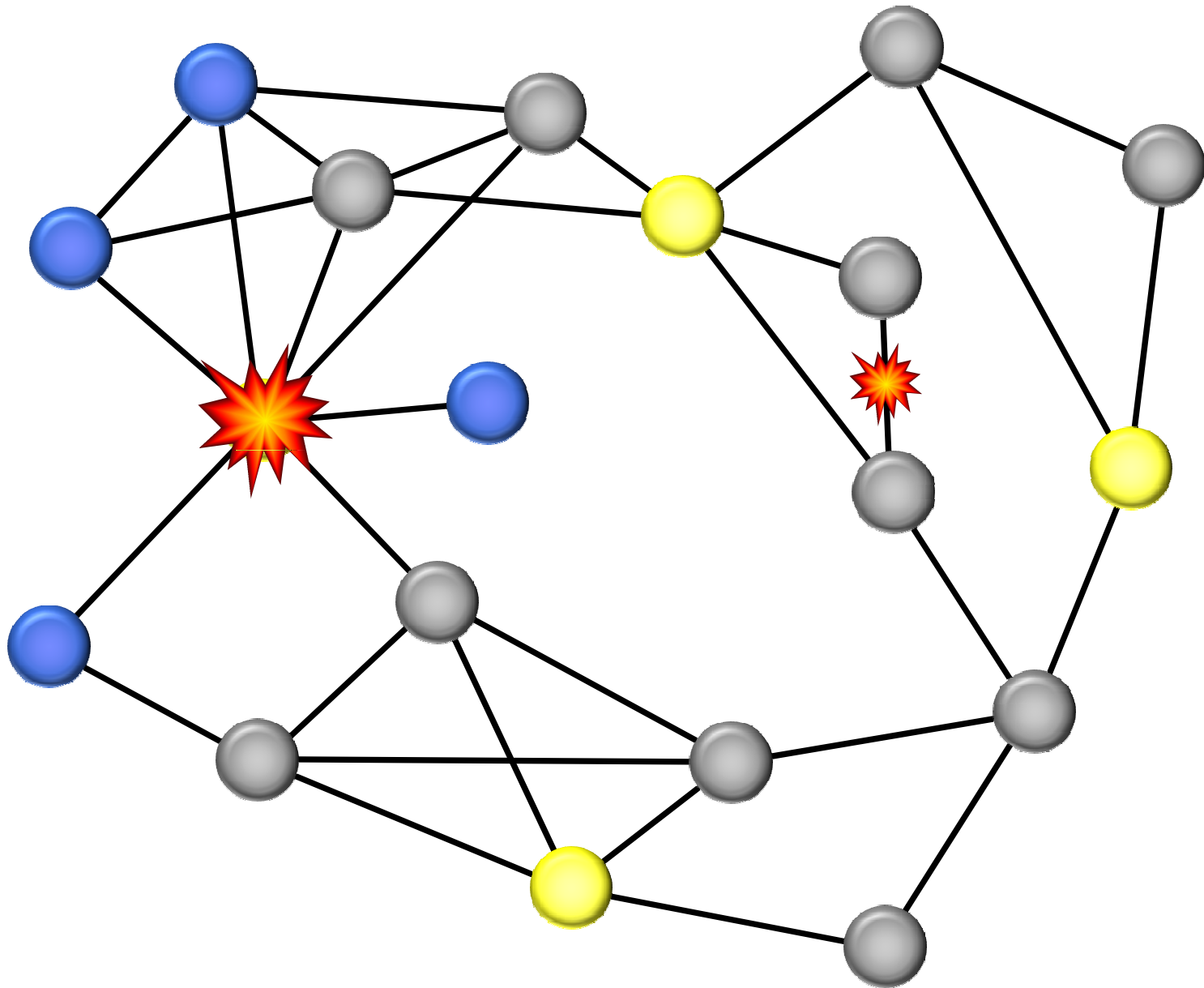
# Motivation by Example



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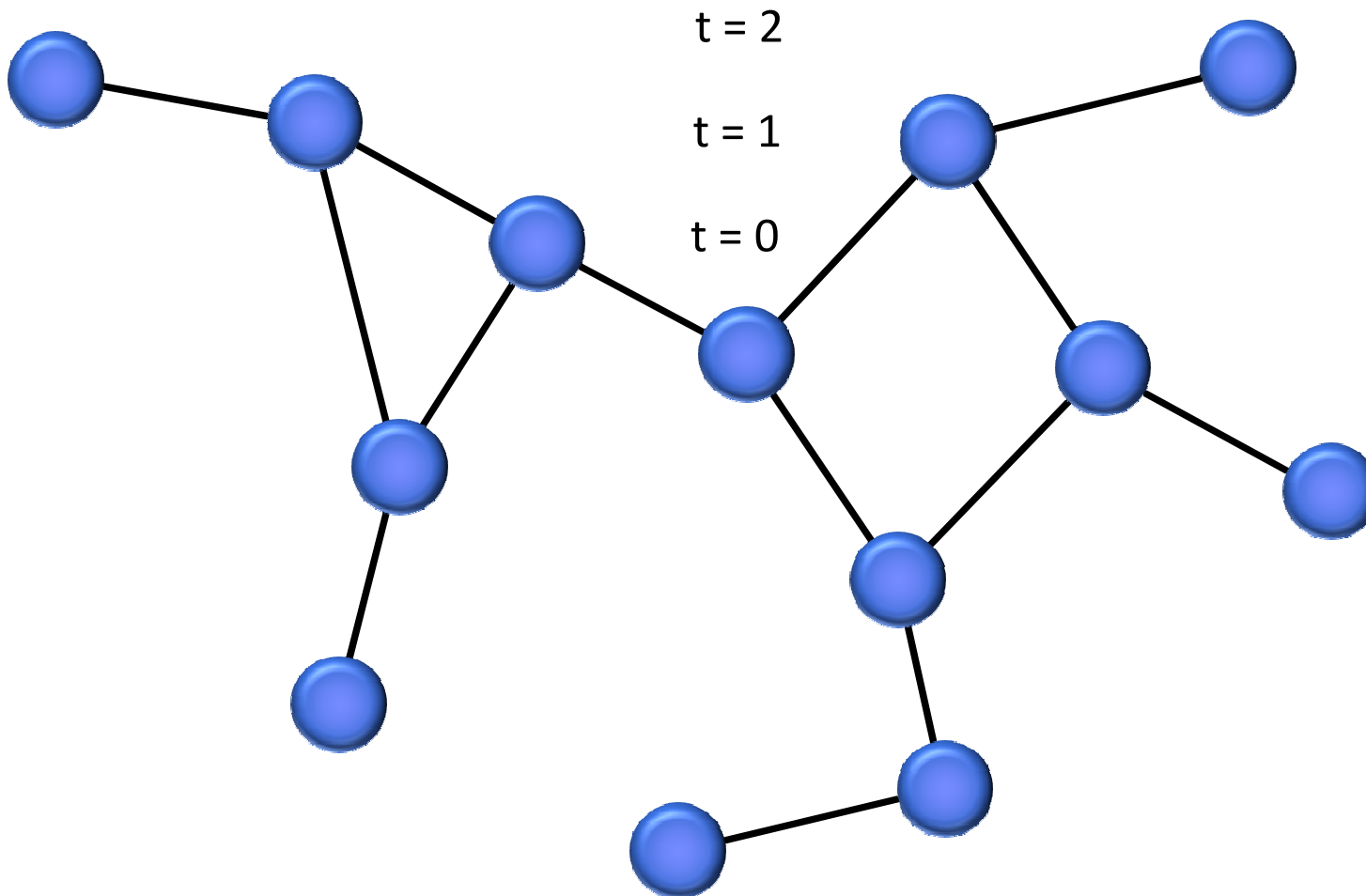


# Motivation by Example



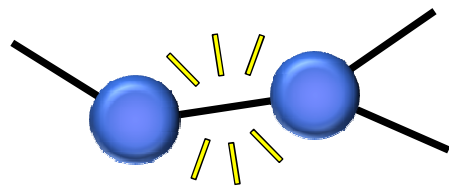
# Model

- Neighborhood model
  - Unbounded message sizes
  - Synchronous rounds

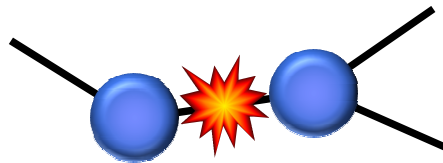


## Model (cont.)

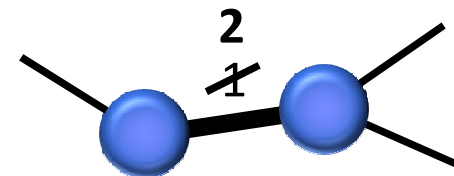
- We say a problem can be **fixed locally** if any solution can be fixed within  $O(1)$  rounds after a graph change.



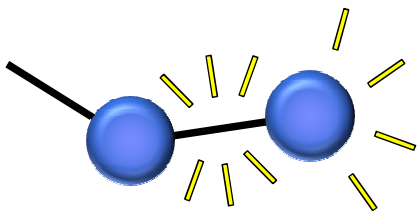
(+e)  
Edge Insertion



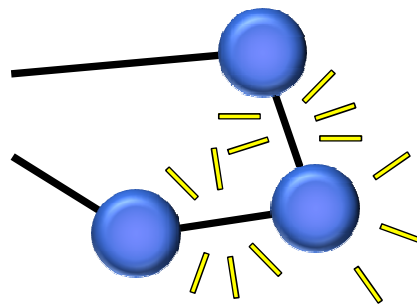
(-e)  
Edge Deletion



( $w \rightarrow w'$ )  
Weight Change

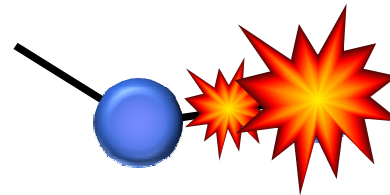


(+v<sub>1</sub>)

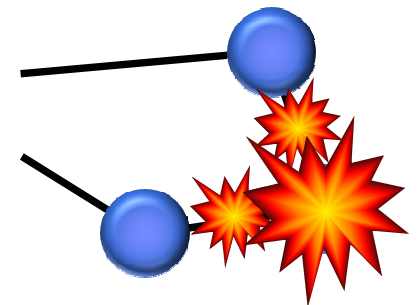


(+v<sub>\*</sub>)

Node Insertion



(-v<sub>1</sub>)

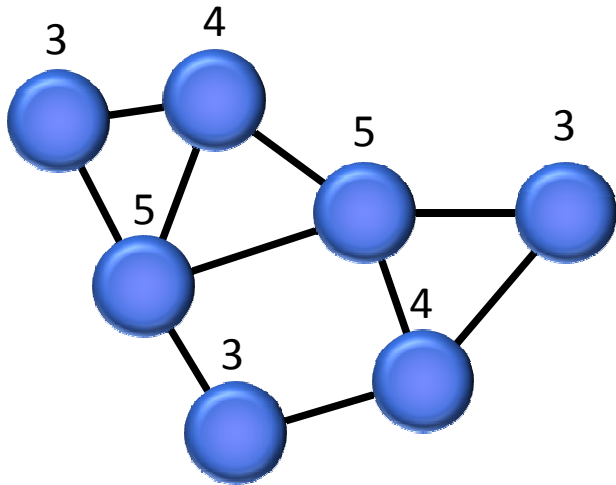


(-v<sub>\*</sub>)

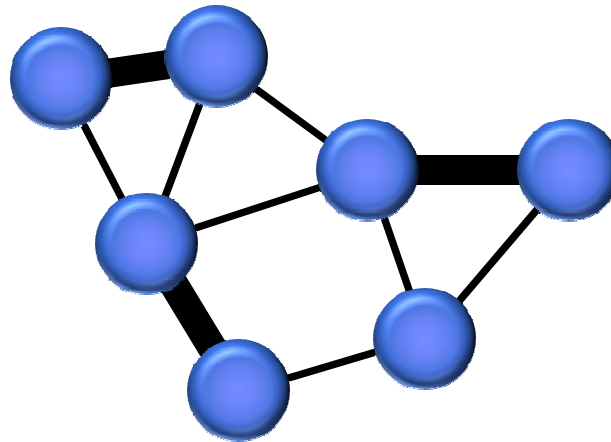
Node Deletion

# Computation vs. Fixing

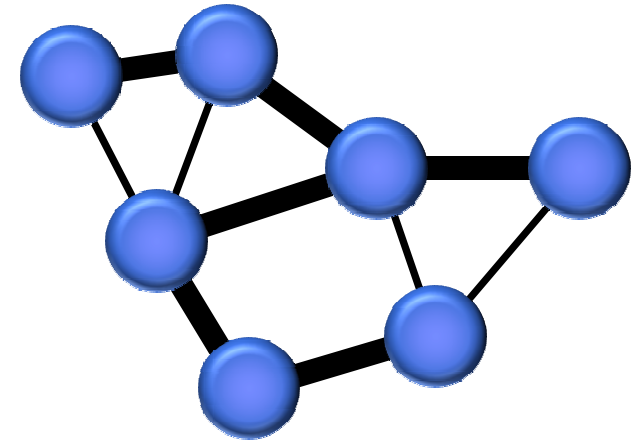
- Computing solutions is very well-studied
- Different “complexity classes” have been defined:



$\Gamma_1$ -Count  
“local”



Maximal Matching  
“polylog”



Spanning Tree  
“global”

- Previous work on local fixing
  - 1995: Maximal Independent Sets (MIS), by Kutten and Peleg
  - 2007:  $O(1)$ -Maximum Weighted Matchings, by Lotker, Patt-Shamir and Rosén

# Problems

	LBound	UBound
$\Gamma_1$ -Count	$\Omega(1)$	$O(1)$
$o(n)$ -MDS	$\Omega(1)$	$O(1)$
MIS	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$
$O(1)$ -MWM	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$
MM	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$
2-MVC	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$
$\Gamma_{\log(n)}$ -Count	$\Omega(\log(n))$	$O(\log(n))$
ST	$\Omega(D)$	$O(D)$
MST	$\Omega(D)$	$O(D)$
SPT	$\Omega(D)$	$O(D)$
Flow	$\Omega(D)$	$O(D)$
Leader	$\Omega(D)$	$O(D)$
Count	$\Omega(D)$	$O(D)$

# Problems

	LBound	UBound	+e	-e	$w \rightarrow w'$	$+v_1$	$-v_1$	$+v_*$	$-v_*$
$\Gamma_1$ -Count	$\Omega(1)$	$O(1)$							
$o(n)$ -MDS	$\Omega(1)$	$O(1)$							
MIS	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$							
$O(1)$ -MWM	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$							
MM	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$							
2-MVC	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$							
$\Gamma_{\log(n)}$ -Count	$\Omega(\log(n))$	$O(\log(n))$							
ST	$\Omega(D)$	$O(D)$							
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Count	$\Omega(D)$	$O(D)$							



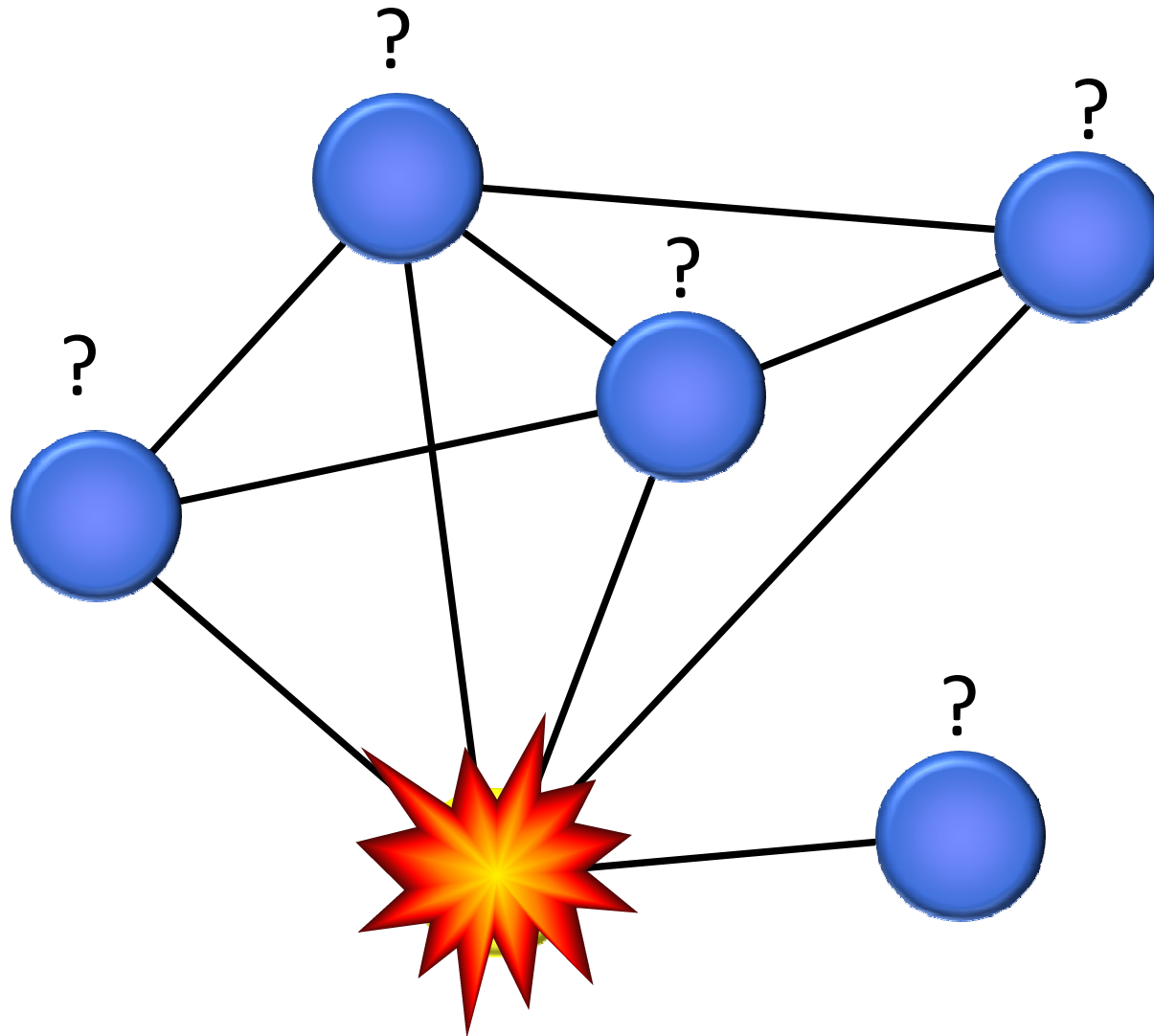
# Problems

	LBound	UBound	+e	-e	$w \rightarrow w'$	+v <sub>1</sub>	-v <sub>1</sub>	+v <sub>*</sub>	-v <sub>*</sub>
$\Gamma_1$ -Count	$\Omega(1)$	$O(1)$	✓	✗		✓	✗	✓	✗
$o(n)$ -MDS	$\Omega(1)$	$O(1)$	✗	✓		✗	✓	✗	✓
MIS	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$	✓	✗		✓	✗	✓	✗
$O(1)$ -MWM	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$	✗	✓	✗	✗	✓	✗	✓
MM	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$	✓	✗		✓	✗	✓	✗
2-MVC	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$	✗	✓		✗	✓	✗	✓
$\Gamma_{\log(n)}$ -Count	$\Omega(\log(n))$	$O(\log(n))$	✓	✗		✓	✗	✓	✗
ST	$\Omega(D)$	$O(D)$	✓	✗		✓	✗	✓	✗
MST	$\Omega(D)$	$O(D)$	✗	✓	✗	✗	✓	✗	✓
SPT	$\Omega(D)$	$O(D)$	✓	✗	✓	✓	✗	✓	✗
Flow	$\Omega(D)$	$O(D)$	✗	✓	✗	✗	✓	✗	✓
Leader	$\Omega(D)$	$O(D)$	✓	✗		✓	✗	✓	✗
Count	$\Omega(D)$	$O(D)$	✗	✓		✗	✓	✗	✓

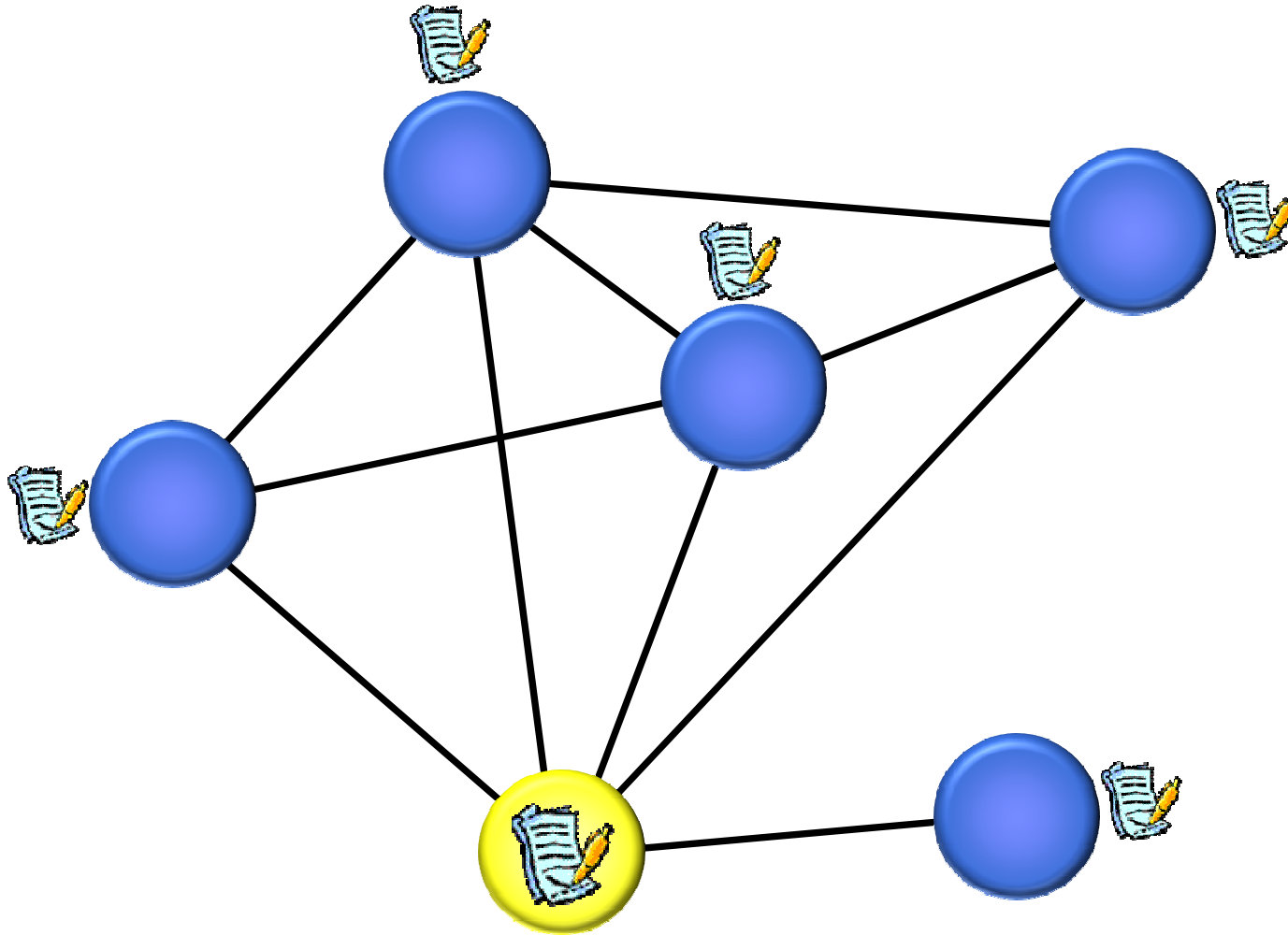
# Results

	LBound	UBound	+e	-e	$w \rightarrow w'$	$+v_1$	$-v_1$	$+v_*$	$-v_*$
$\Gamma_1$ -Count	$\Omega(1)$	$O(1)$	✓	✓		✓	✓	✓	✓
$o(n)$ -MDS	$\Omega(1)$	$O(1)$	✗	✗		✗	✗	✗	✗
MIS	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$	✓	✓		✓	✓	✓	✓
$O(1)$ -MWM	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$	✓	✓	✓	✓	✓	✓	✓
MM	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$	✓	✓		✓	✓	✓	✓
2-MVC	$\Omega(\sqrt{\log(n)})$	$O(\log(n))$	✓	✓		✓	✓	✓	✓
$\Gamma_{\log(n)}$ -Count	$\Omega(\log(n))$	$O(\log(n))$	✗	✗		✗	✗	✗	✗
ST	$\Omega(D)$	$O(D)$	✓	✗		✓	✓	✓	✗
MST	$\Omega(D)$	$O(D)$	✗	✗	✗	✓	✓	✗	✗
SPT	$\Omega(D)$	$O(D)$	✗	✗	✗	✓	✓	✗	✗
Flow	$\Omega(D)$	$O(D)$	✗	✗	✗	✓	✓	✗	✗
Leader	$\Omega(D)$	$O(D)$	✓	✓		✓	✓	✓	✓
Count	$\Omega(D)$	$O(D)$	✓	✓		✗	✗	✗	✗

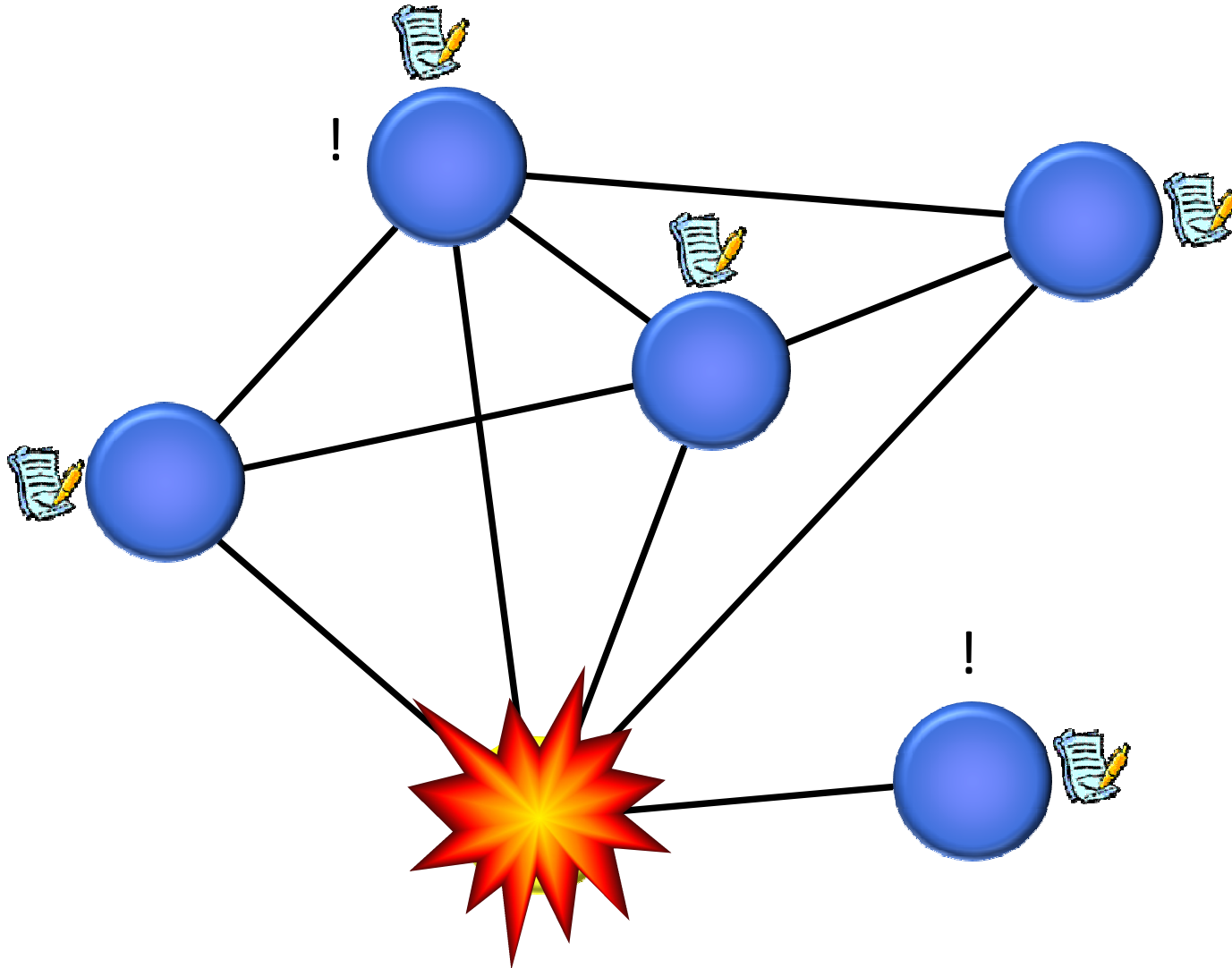
# Maximal Independent Set (MIS)



“Last Will”: during settling



“Last Will”: in action



## $o(n)$ -Minimum Dominating Set

- We know algorithms which compute a  $o(n)$ -MDS in constant time [Kuhn et al., 2005]
- But we can construct  $o(n)$ -MDS solutions which cannot be fixed locally!

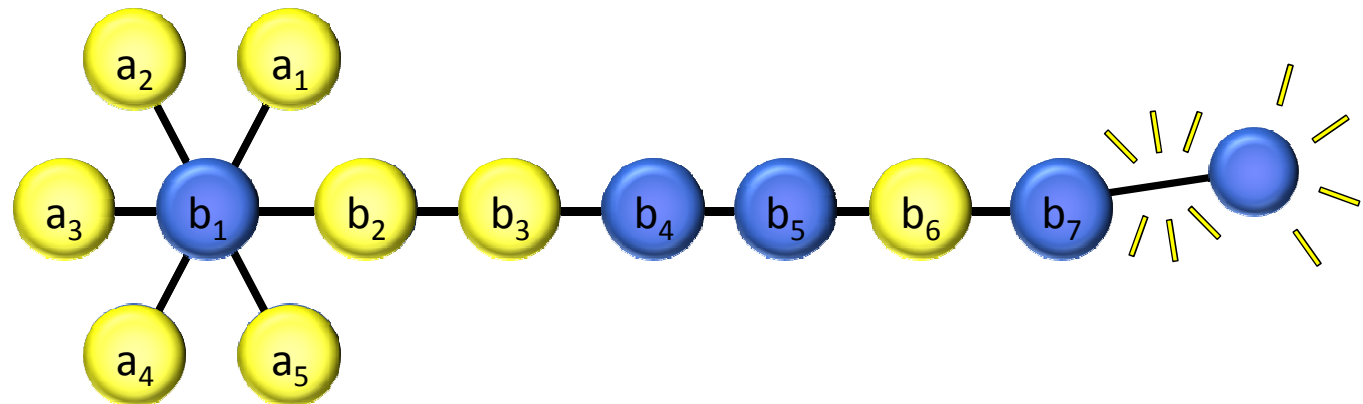
Recipe for a  $k$ -MDS which cannot be fixed within  $c$  steps:

$$x = \lfloor (k - 1)(c + 1) \rfloor, y = 3c + 1$$

$$V = (a_1, a_2, \dots, a_x, b_1, b_2, \dots, b_y)$$

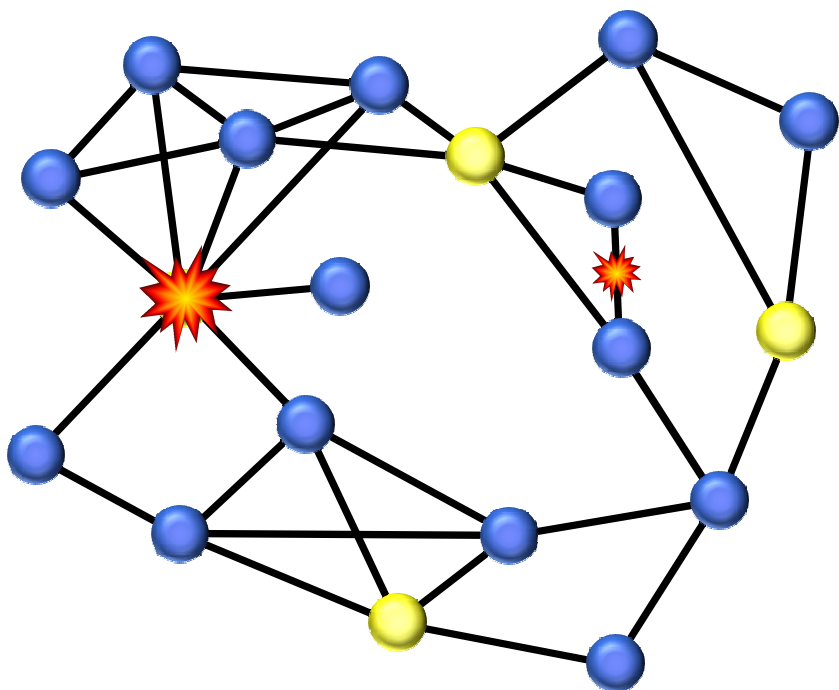
$$E = \{(a_i, b_1) \mid 1 \leq i \leq x\} \cup \{(b_i, b_{i+1}) \mid 1 \leq i \leq y\}$$

For  $k = 2.8$ ,  $c = 2$ ,  $x = 5$  and  $y = 7$ :



# Conclusion

- Traditional distributed complexity classes don't tell the whole story.
- A set of orthogonal “fixing complexity” classes may be interesting!



	LBound	UBound	+e	-e	$w \rightarrow w'$	$+v_1$	$-v_1$	$+v_*$	$-v_*$
$\Gamma_1$ -Count	$\Omega(1)$	$O(1)$	✓	✓		✓	✓	✓	✓
$o(n)$ -MDS	$\Omega(1)$	$O(1)$	✗	✗		✗	✗	✗	✗
MIS	$\Omega(v \log(n))$	$O(\log(n))$	✓	✓		✓	✓	✓	✓
$O(1)$ -MWM	$\Omega(v \log(n))$	$O(\log(n))$	✓	✓	✓	✓	✓	✓	✓
MM	$\Omega(v \log(n))$	$O(\log(n))$	✓	✓		✓	✓	✓	✓
2-MVC	$\Omega(v \log(n))$	$O(\log(n))$	✓	✓		✓	✓	✓	✓
$\Gamma_{\log(n)}$ -Count	$\Omega(\log(n))$	$O(\log(n))$	✗	✗		✗	✗	✗	✗
ST	$\Omega(D)$	$O(D)$	✓	✗		✓	✓	✓	✗
MST	$\Omega(D)$	$O(D)$	✗	✗	✗	✓	✓	✗	✗
SPT	$\Omega(D)$	$O(D)$	✗	✗	✗	✓	✓	✗	✗
Flow	$\Omega(D)$	$O(D)$	✗	✗	✗	✓	✓	✗	✗
Leader	$\Omega(D)$	$O(D)$	✓	✓		✓	✓	✓	✓
Count	$\Omega(D)$	$O(D)$	✓	✓		✗	✗	✗	✗

# Thanks!

Questions & Comments?

