

# Lost in Space

or

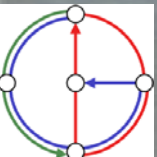
# Positioning in Sensor Networks

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*Roger Wattenhofer*



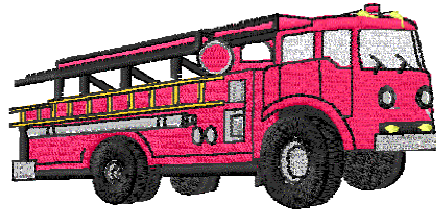
**ETH**

Eidgenössische Technische Hochschule Zürich  
Swiss Federal Institute of Technology Zurich

Mark '99  
Dorais

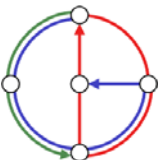
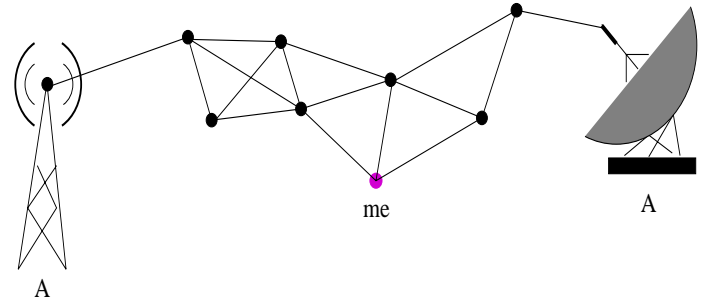
# Positioning

- What is positioning (a.k.a. localization)?
  - Deduce coordinates
  - GPS “software version”

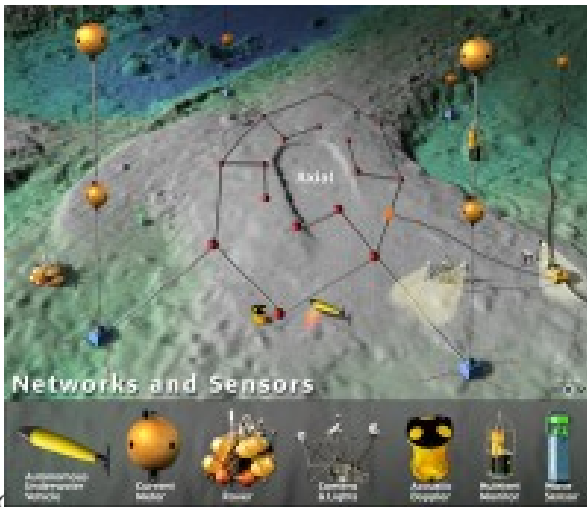
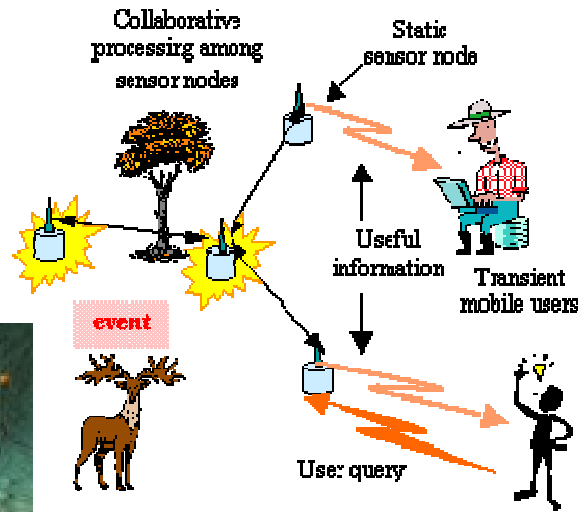
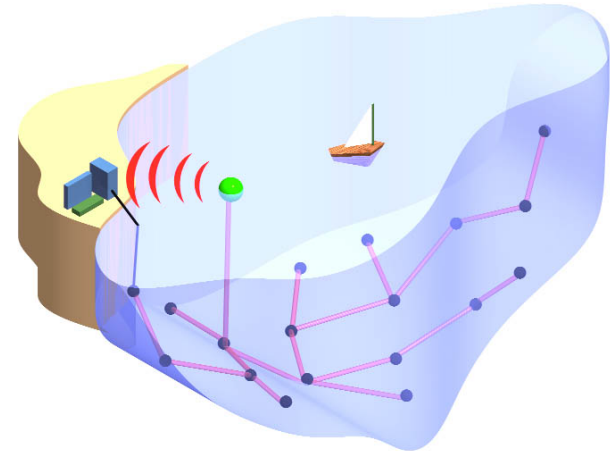
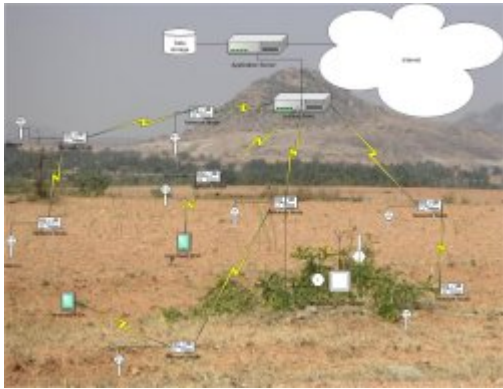


- Why positioning?
  - Sensible sensor networks
  - Heavy/costly localization hardware
  - Geometric routing benefits

- Idea:
  - (Small) set of anchors
  - Others: location =  $f(\text{network}, \text{communication}, \text{measurements})$



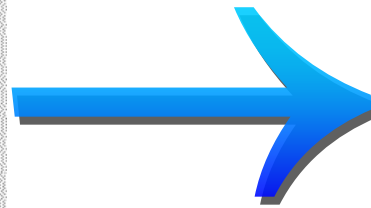
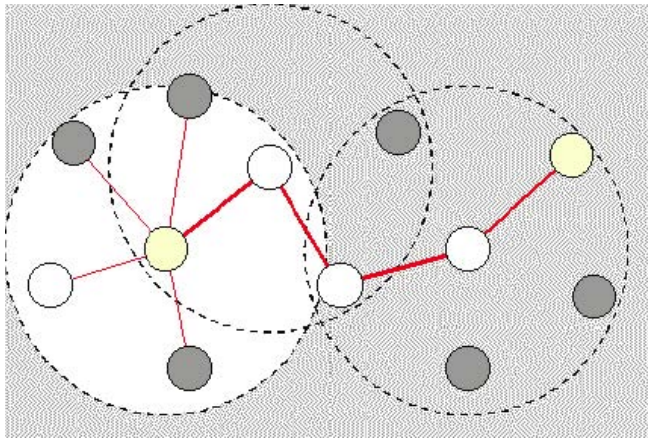
# Sensor Networks



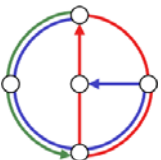
# Our Perspective



Theory



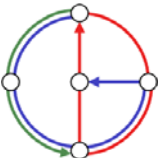
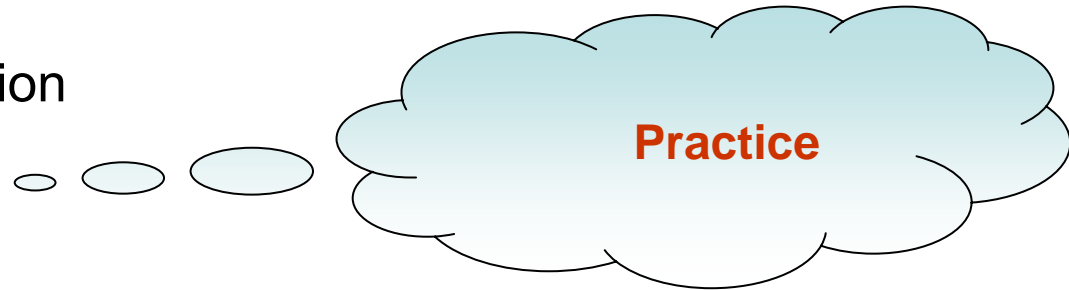
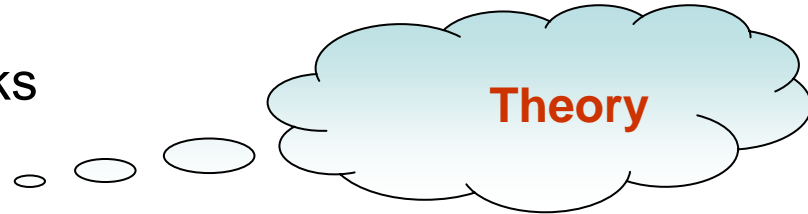
Practice



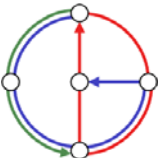
# Positioning – As We See It



- Models of Sensor Networks
- Positioning Algorithms
- Hardware Description
- Experiments
- Lessons
- Future Work



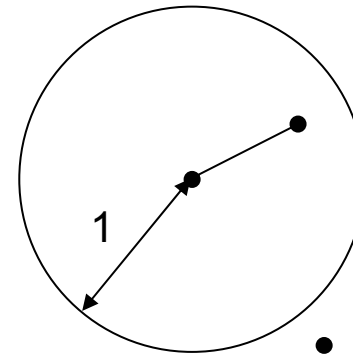
# Part I: Theory



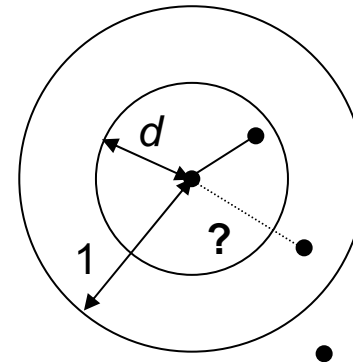
# Models of Sensor Networks



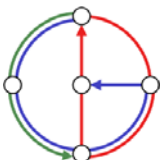
- Unit Disk Graph (UDG)
  - [Clark *et al*, 1990]
  - Widely used **abstraction**



- Quasi-Unit Disk Graph (qUDG)
  - [Krumke *et al*, 2001]
  - [Barriere *et al*, 2003]
  - [Kuhn *et al*, 2003]
  - **More realistic?**



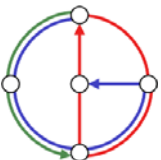
- “**well-behaved**”  $\Rightarrow$  allow proofs



# Available Information



- T[D]oA:time
  - GPS
  - Cricket [Priyantha *et al*, 2000]
- RSS: signal strength
  - RADAR [Bahl, Padmanabhan, 2000]
- Imply distance
  
- AoA: angle
  - APS using AoA [Niculescu, Nath, 2003]
  
- Relative distance to anchors
  - APiT [He *et al*, 2003]

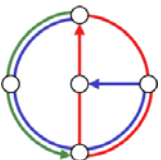




# Positioning Algorithms

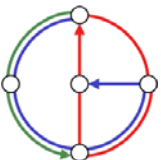


- Based on (q)UDG
  - (sometimes) **provable** statements
  - Abstraction  $\Rightarrow$  rough idea
- Virtual Coordinates Algorithm [Moscibroda *et al*, 2004]
  - Linear programming
  - **Complex**, time-consuming
  - 100-node network: several minutes on desktop
- GHoST, HS [Bischoff, W., 2004]
  - Dense networks
  - Optimal in 1D
  - **UDG crucial**



# Positioning Algorithms... cont'd

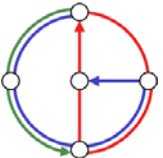
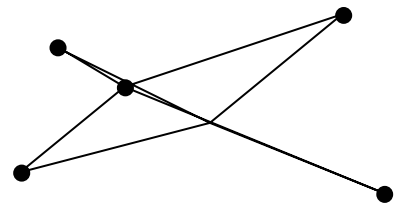
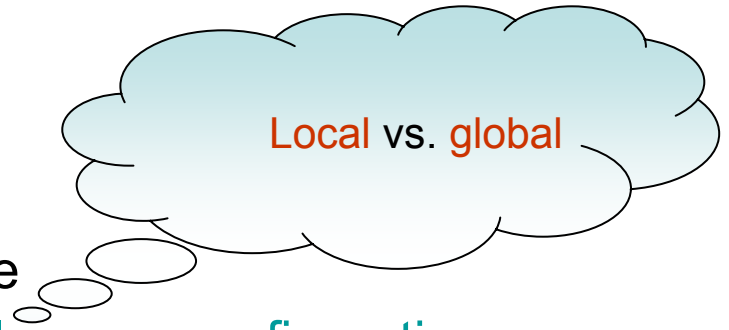
- APS [Niculescu, Nath, 2001 & 2003]
  - Hop or distance based
  - Given distance estimate, use GPS triangulation
  - Least-squares optimization
  - Isotropic network helpful
- General graphs
  - Given inter-node distances
  - Also: **Internet** graph (latencies)
- Example: Spring Algorithms
  - Internet: Vivaldi [Dabek *et al*, 2004]
  - Ad hoc [Rao *et al*, 2003]



# Spring Algorithm



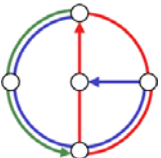
- Most **practical**?
- Originally: graph drawing
- Idea
  - Edge = spring
  - Rest length = distance
  - **Embedding** = **minimal power configuration**
- Algorithm
  - Steepest descent, numerical methods
  - Simple:
    - New position = average of neighbors
    - Iterate



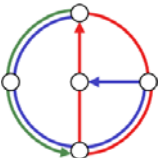
# Our View = Assumptions



- Minimal hardware
  - Low storage
  - Low computing power
  - Basic RSS measurements
- Short range
  - Few meters
  - (RADAR: building – several dekameters)



# Part II: Practice

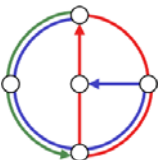


# Hardware Description

- ESB
  - [scatterweb.com](http://scatterweb.com)
  - 32kHz CPU
  - 2kB RAM
  - Sensors and actuators
- RSS:
  - **Indirectly** via packet loss
- New version:
  - Actual RSS measurable at receiver
- “Battery with Antenna”

Desktop:

- 3GHz
- 512MB
- **Factor  $10^5$**

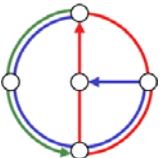


# “software version” RSS

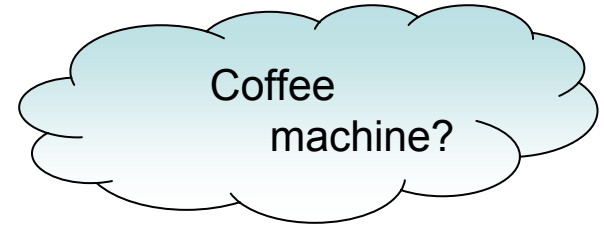
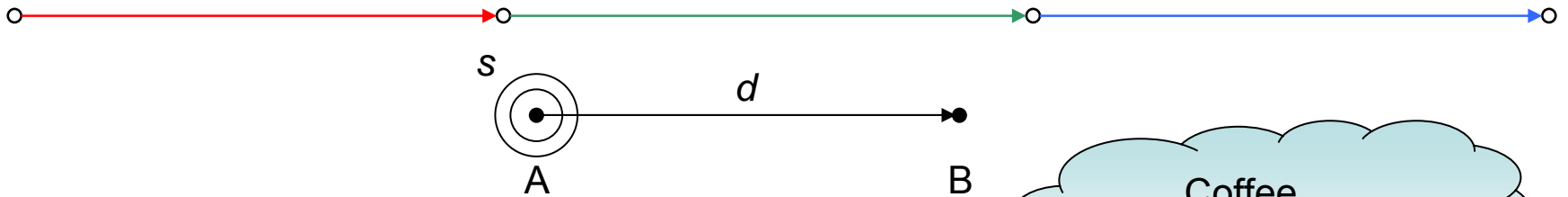


- Older ESB (software) version
  - @sender: vary transmission power
    - Via potentiometer controlling current to transceiver
    - Value  $s$  between 0 and 99
    - Write  $s$  into packet
    - Repeat  $x$  times
  - @receiver: count number received packets
    - per  $s$
  - Measurement: packet loss
- Requirement
  - Distance increase  $\rightarrow$  power increase
  - Correlation: to be determined
- New version (software):
  - Direct read out

**Future work!**

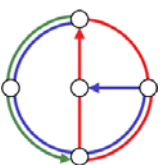
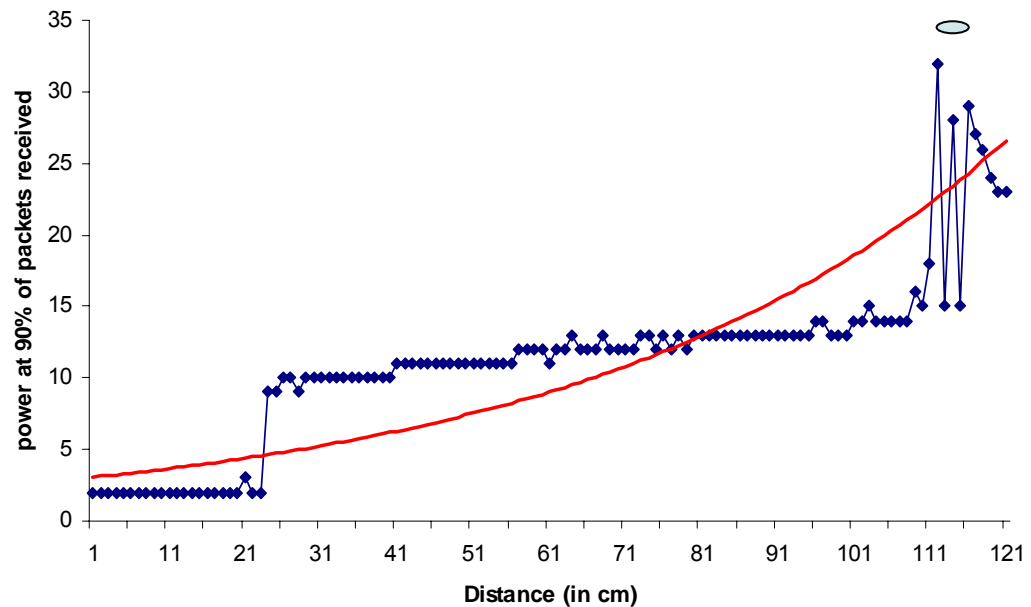


# Experiment 1 – “Laboratory”



- Power vs. Distance
  - A sends at power level  $s$
  - $x = 100$  times
  - $d = 1..120\text{cm}$

- Minimum
- 90%



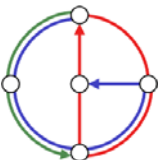


# Original Algorithm

- Spring Embedding
  - Good for “easy” networks
- Power-to-distance
  - Inverse of previous experiments

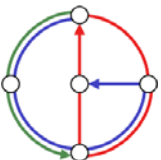
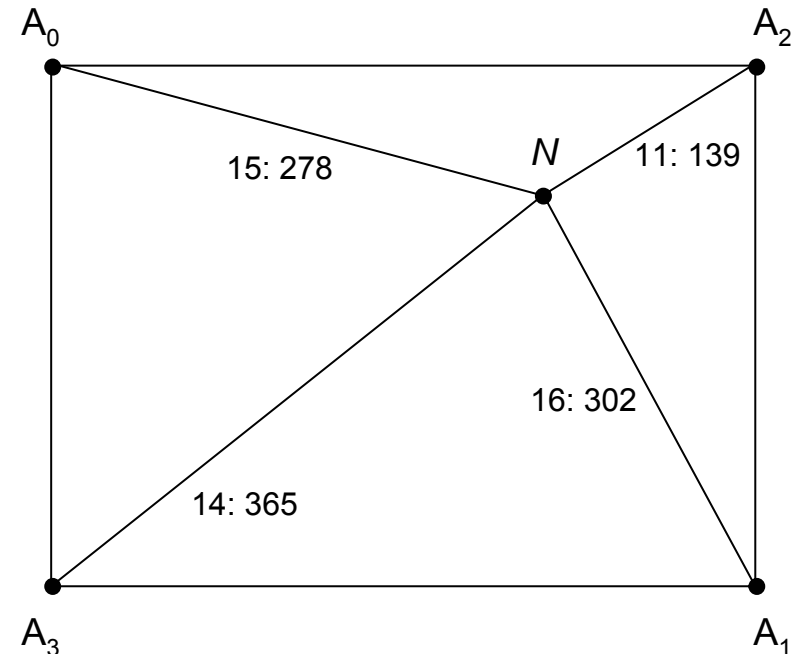


- Results
  - **Unusable!**

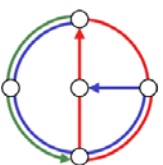
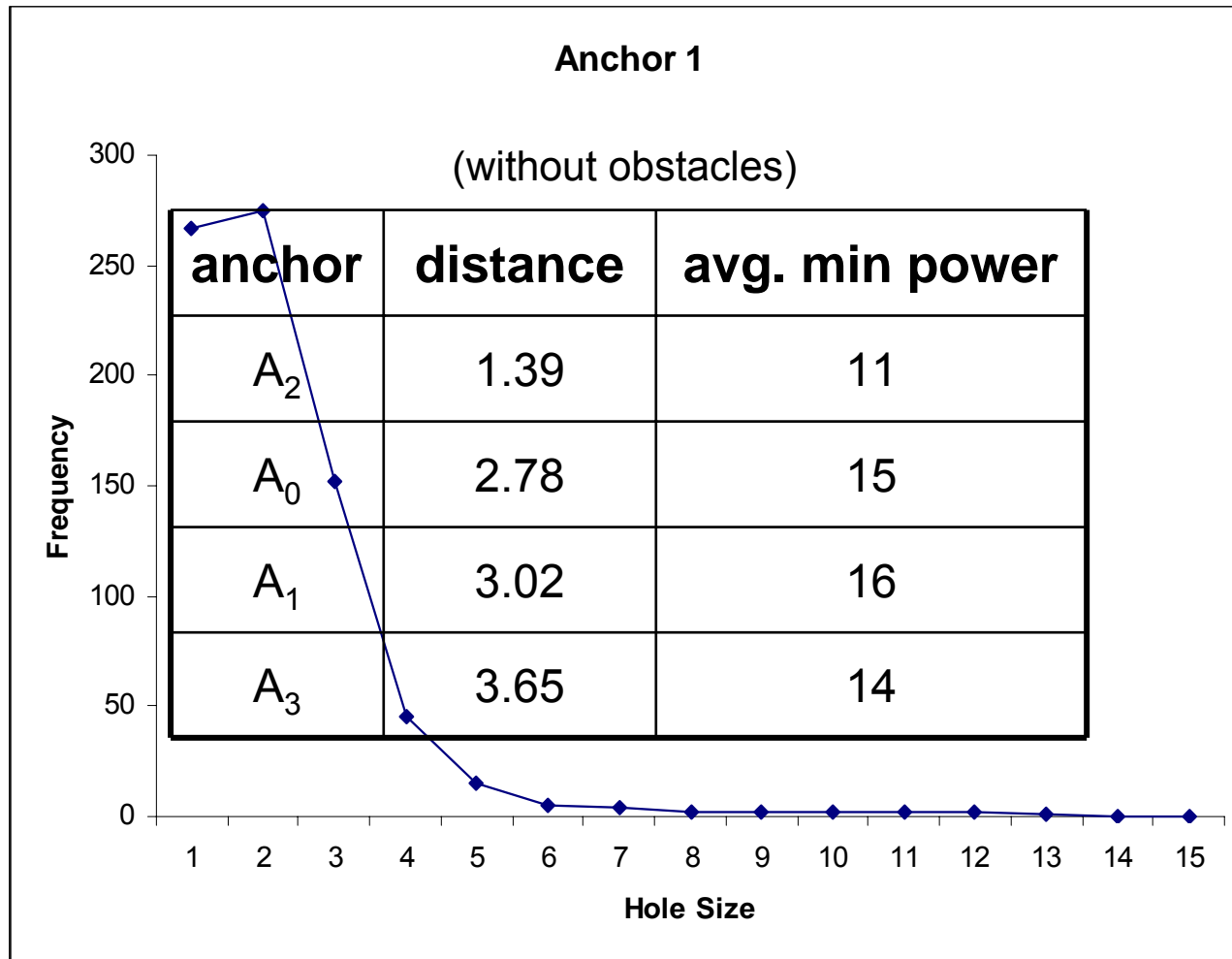


# Experiment 2 – “Room”

- Localization in the plane
  - Rectangle: 4m x 3m
  - 4 anchors: corners
  - Test node: inside
- Each anchor  $A_i$ 
  - Send packet  $s = 0..99$
  - Next anchor
- Test node  $N$ 
  - Record packets received



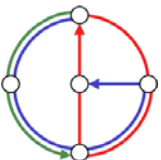
# Experiment 2 – “Room” ... Results



# Experiment 3 – “Network”



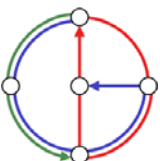
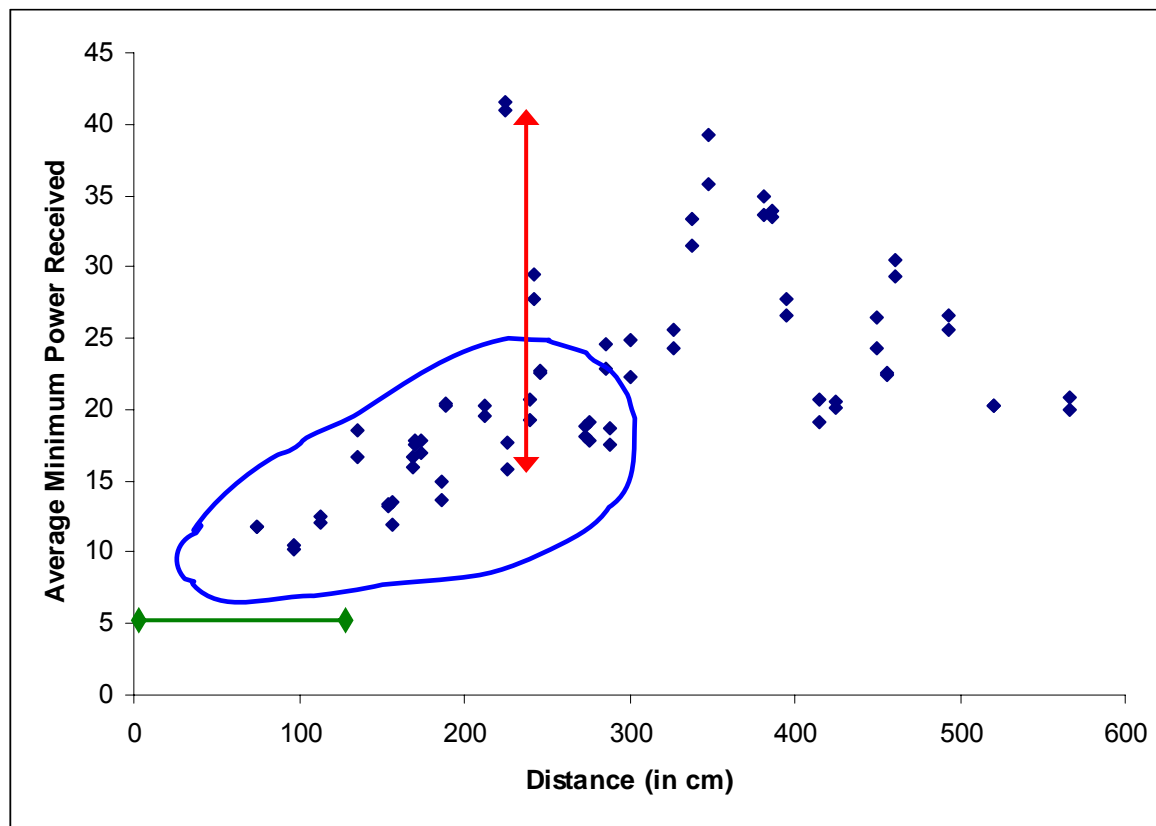
- 9 nodes in a room
  - Distances: 1..6m
- 1 sender at a time
  - Send 1 packet at each level
  - Others: record minimum received
  - Report previous minima
- Round robin
- Minima:
  - Good approximation
  - Storage: save factor 100 per round



# Experiment 3 – “Network” ... Results



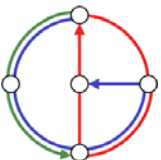
- Error
  - Almost 30 units for same distance
  - Exp. 1: “nicer” curve
- Longer range effects?
- Symmetry!



# Lessons



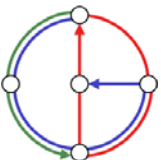
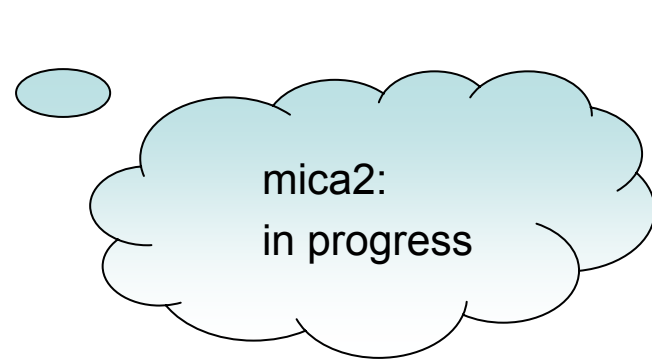
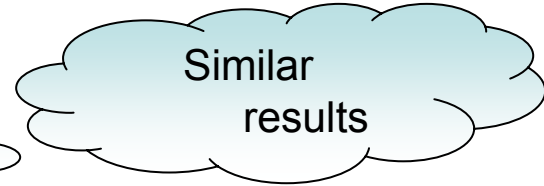
- Average minimum
  - Stable
  - Good approximation
  - Saves storage
- Symmetric links
- Power versus Distance
  - Strongly environment dependant
  - Measurements between two nodes
    - ➔ Not generalizable
- RSSI in sensor networks: good, but not for “reasonable” localization



# Future Work



- Here: more questions than answers
- Hardware RSS measurements
  - Indication given by reviewer
- Same experiments – different **hardware**
  - Same results/trend?
- Long **range** vs. short range
- More **environments**
- New **models**





Questions?  
Comments?

